

Technical data sheet

LMB24-SR

Modulating, Non-Spring Return, 24 V, for DC 2...10 V or 4...20 mA





Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Power consumption in operation	1.5 W
	Power consumption in rest position	0.4 W
	Power consumption for wire sizing	3 VA
	Transformer sizing	3 VA (class 2 power source)
	Electrical Connection	18 GA plenum cable with 1/2" conduit connector, degree of protection NEMA 2 / IP54, 3 ft [1 m] 10 ft [3 m] and 16ft [5 m]
	Overload Protection	electronic throughout 095° rotation
Functional data	Torque motor	45 in-lb [5 Nm]
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Direction of motion motor	selectable with switch 0/1
	Manual override	external push button
	Angle of rotation	Max. 95°
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	95 s / 90°
	Running time motor note	constant, independent of load
	Noise level, motor	35 dB(A)
	Shaft Diameter	1/45/8" round, centers on 5/8", 3/4" clamp available
	Position indication	Mechanically, 3065 mm stroke
Safety data	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU and 2014/35/EU; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC
	Quality Standard	ISO 9001
	Ambient temperature	-22122°F [-3050°C]
	Storage temperature	-40176°F [-4080°C]
	Ambient humidity	Max. 95% RH, non-condensing
	Servicing	maintenance-free
Materials	Housing material	UL94-5VA

Footnotes †Rated Impulse Voltage 800V, Type action 1, Control Pollution Degree 3.





Application	For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft from 1/4" up to 5/8" in diameter by means of its universal clamp. Shafts up to 3/4" diameter can be accommodated by an accessory clamp. The actuator operates in response to a 210 V, or with the addition of a 500 Ω resistor, a 420 mA control input from an electronic controller or positioner. A 210 V feedback signal is provided for position indication or master-slave applications.
Operation	The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.
	The LMB series provides 95° of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.
	The LMB24-SR actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.
	Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.
Typical specification	Proportional control damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft from 1/4" to 5/8". Actuators must provide control in response to a control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Accessories

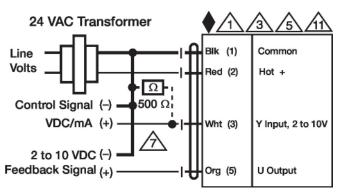
Battery backup system, for non-spring return models Battery, 12 V, 1.2 Ah (two required)	NSV24 US
Pattory 12 1/ 12 Ab (two required)	
ballery, 12 v, 1.2 All (lwo required)	NSV-BAT
Feedback potentiometer 140 Ω add-on, grey	P140A GR
Feedback potentiometer 500 Ω add-on, grey	P500A GR
Feedback potentiometer 1 k Ω add-on, grey	P1000A GR
Feedback potentiometer 2.8 k Ω add-on, grey	P2800A GR
Feedback potentiometer 5 k Ω add-on, grey	P5000A GR
Feedback potentiometer 10 k Ω add-on, grey	P10000A GR
Auxiliary switch 1 x SPDT add-on	S1A
Auxiliary switch 2 x SPDT add-on	S2A
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	Feedback potentiometer 500 Ω add-on, grey Feedback potentiometer 1 k Ω add-on, grey Feedback potentiometer 2.8 k Ω add-on, grey Feedback potentiometer 5 k Ω add-on, grey Feedback potentiometer 10 k Ω add-on, grey Auxiliary switch 1 x SPDT add-on

Electrical installation

 $\bigwedge_{}$ Provide overload protection and disconnect as required.

- Actuators may also be powered by DC 24 V. Only connect common to negative (-) leg of control circuits. A 500 Ω resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.
- \overline Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.





2...10 V / 4...20 mA Control

Dimensions

