





5-year warranty





# **Technical data**

F	lectri	ical	da	ta

Nominal voltage	AC/DC 24 V
Nominal voltage frequency	50/60 Hz
Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
Power consumption in operation	7.5 W
Power consumption in rest position	3 W
Transformer sizing	10 VA
Auxiliary switch	2 x SPDT, 3 A resistive (0.5 A inductive) @ AC 250 V, one set at 10°, one adjustable 1090°
Switching capacity auxiliary switch	3 A resistive (0.5 A inductive) @ AC 250 V
Electrical Connection	(2) 18 GA appliance cables, 1 m, with 1/2" conduit connectors
Overload Protection	electronic throughout 095° rotation
Electrical Protection	actuators are double insulated
Torque motor	190 in lb [20 Nm]

## **Functional data**

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Electrical Protection	actuators are double insulated	
Torque motor	180 in-lb [20 Nm]	
Operating range Y	210 V	
Operating range Y note	420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)	
Input Impedance	100 k $\Omega$ for 210 V (0.1 mA), 500 $\Omega$ for 420 mA, 1500 $\Omega$ for PWM, On/Off and Floating point	
Operating range Y variable	Start point 0.530 V End point 2.532 V	
Operating modes optional	variable (VDC, PWM, on/off, floating point)	
Position feedback U	210 V	
Position feedback U note	Max. 0.5 mA	
Position feedback U variable	VDC variable	
Direction of motion motor	selectable with switch 0/1	
Direction of motion fail-safe	reversible with cw/ccw mounting	
Manual override	5 mm hex crank (3/16" Allen), supplied	
Angle of rotation	95°	
Angle of rotation note	adjustable with mechanical end stop, 3595°	
Running Time (Motor)	150 s / 90°	
Running time motor variable	70220 s	
Running time fail-safe	<20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]	
Adaptation Setting Range	off (default)	
Override control	MIN (minimum position) = 0%	
	MID (intermediate position) = 50%	
	MAX (maximum position) = 100%	
Noise level, motor	40 dB(A)	
Noise level, fail-safe	62 dB(A)	
Position indication	Mechanical	



# Technical data sheet AFB24-MFT-S

#### Safety data

Power source UL	Class 2 Supply	
Degree of protection IEC/EN	IP54	
Degree of protection NEMA/UL	NEMA 2	
Enclosure	UL Enclosure Type 2	
Agency Listing	cULus listed to UL60730-1A:02; UL 60730-2-14:02 and CAN/CSA-E60730-1:02	
Quality Standard	ISO 9001	
UL 2043 Compliant	Suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the IMC	
Ambient humidity	Max. 95% RH, non-condensing	
Ambient temperature	-22122°F [-3050°C]	
Storage temperature	-40176°F [-4080°C]	
Servicing	maintenance-free	
Weight	4.2 lb [1.9 kg]	
Housing material	Galvanized steel and plastic housing	

#### **Footnotes**

Weight

Materials

†Rated Impulse Voltage 800V, Type of Action 1.AA.B, Control Pollution Degree 3.

When not mechanically linked, actuators must be wired in parallel.

## **Product features**

## Default/Configuration

Default parameters for 2 to 10 VDC applications of the AF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

## Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication for primary and secondary applications. Two AF's can be piggybacked for torque loads to max. 360 in-lb. Minimum 3/4" diameter shaft. OR Maximum of three AF's can be piggybacked for torque loads to max. 432 in-lb. Minimum 3/4" diameter shaft. Primary and secondary wiring for either configuration. Actuators must be mechanically linked.

## Operation

The AF..24-MFT actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the physical damper or valve mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its 95° of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuators's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The AF..24-MFT is mounted directly to control shafts up to 1.05" diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The AF..24-MFT actuator is shipped at 5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

<sup>\*</sup>Variable when configured with MFT options.



## **Technical data sheet**

AFB24-MFT-S

#### Typical specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback or primary and secondary applications. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

#### **Factory settings**

Default parameters for 2 to 10 VDC applications of the AF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

## **Accessories**

Electrical accessories	Description	Туре
	DC Voltage Input Rescaling Module	IRM-100
	Auxiliary switch, mercury-free	P475
	Auxiliary switch, mercury-free	P475-1
	Convert Pulse Width Modulated Signal to a 210 V Signal for Belimo	PTA-250
	Proportional Actuators	
	Positioner for wall mounting	SGA24
	Positioner for front-panel mounting	SGF24
	Cable conduit connector 1/2"	TF-CC US
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to LonWorks	UK24LON
	Gateway MP to Modbus RTU	UK24MOD
	Resistor, 500 $\Omega$ , 1/4" wire resistor with 6" pigtail wires	ZG-R01
	Resistor kit, 50% voltage divider	ZG-R02
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40



#### **Technical data sheet** AFB24-MFT

## Mechanical accessories

Description	Туре
Anti-rotation bracket, for AF / NF	AF-P
Shaft extension 240 mm Ø20 mm for damper shaft Ø 822.7 mm	AV8-25
End stop indicator	IND-AFB
Shaft clamp reversible, for central mounting, for damper shafts Ø12.7 /	K7-2
19.0 / 25.4 mm	
Ball joint suitable for damper crank arm KH8 / KH10, Multipack 10 pcs.	KG10A
Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8
Damper crank arm Slot width 8.2 mm, clamping range Ø1425 mm	KH10
Damper crank arm Slot width 8.2 mm, for Ø1.05"	KH12
Damper crank arm Slot width 8.2 mm, clamping range Ø1018 mm	KH8
Actuator arm, for 3/4" shafts, clamping range Ø1022 mm, Slot width 8.2 mm	KH-AFB
Push rod for KG10A ball joint 36" L, 3/8" diameter	SH10
Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
Wrench 0.32 in and 0.39 in [8 mm and 10 mm]	TOOL-06
Retrofit clip	Z-AF
Mounting bracket for AF	ZG-100
Mounting bracket	ZG-101
Dual actuator mounting bracket.	ZG-102
Mounting bracket	ZG-109
Linkage kit	ZG-110
Mounting bracket	ZG-118
for AF / NF	
Jackshaft mounting bracket.	ZG-120
Mounting kit for linkage operation for flat and side installation	ZG-AFB
Mounting kit for foot mount installation	ZG-AFB118
Damper clip for damper blade, 3.5" width.	ZG-DC1
Damper clip for damper blade, 6" width.	ZG-DC2
1" diameter jackshaft adaptor (11" L).	ZG-JSA-1
1-5/16" diameter jackshaft adaptor (12" L).	ZG-JSA-2
1.05" diameter jackshaft adaptor (12" L).	ZG-JSA-3
Weather shield 330x203x152 mm [13x8x6"] (LxBxH)	ZS-100
Base plate, for ZS-100	ZS-101
Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150
Explosion proof housing 406x254x164 mm [16x10x6.435"] (LxBxH), UL and CSA, Class I, Zone 1&2, Groups B, C, D, (NEMA 7), Class III, Hazardous	ZS-260
(classified) Locations	
Weather shield 438x222x140 mm [17-1/4x8-3/4x5-1/2"] (LxBxH), NEMA	ZS-300
4X, with mounting brackets	
Weather shield 438x222x140 mm [17-1/4x8-3/4x5-1/2"] (LxBxH), NEMA	ZS-300-5
4X, with mounting brackets	
Shaft extension 1/2"	ZS-300-C1
Shaft extension 3/4"	ZS-300-C2
Shaft extension 1"	ZS-300-C3
Base plate extension	Z-SF
	ZG-JSL
Description	Туре
Connection cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	ZTH US
Service Tool, with ZIP-USB function, for programmable and communicative Belimo actuators, VAV controller and HVAC performance	Δ1Π U3
devices	
	MET D
Belimo PC-Tool, Software for adjustments and diagnostics Signal simulator, Power supply AC 120 V	MFT-P PS-100
Signal simulator, rower supply AC 120 V	1 2-100

# **Electrical installation**



Tools

# Warning! Live electrical components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks.



Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

 $\label{thm:meets} \mbox{Meets cULus requirements without the need of an electrical ground connection.}$ 

Apply only AC line voltage or only UL-Class 2 voltage to the terminals of auxiliary switches.

Mixed or combined operation of line voltage/safety extra low voltage is not allowed.

(A) Actuators with appliance cables are numbered.

igwedge Provide overload protection and disconnect as required.

Actuators may also be powered by DC 24 V.

Two built-in auxiliary switches (2x SPDT), for end position indication, interlock control, fan startup, etc.

Only connect common to negative (-) leg of control circuits.

 $\bigwedge$  A 500  $\Omega$  resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.

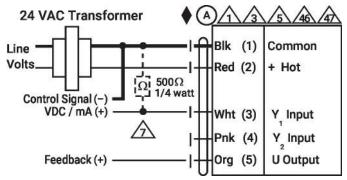
Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 V line.
For triac sink the Common connection from the actuator must be connected to the Hot

For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.

🛕 IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).

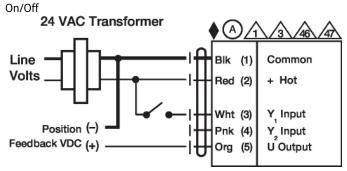
Actuators may be controlled in parallel when not mechanically linked. Current draw and input impedance must be observed.

Master-Slave wiring required for piggy-back applications when mechanically linked. Feedback from Master to control input(s) of Slave(s).

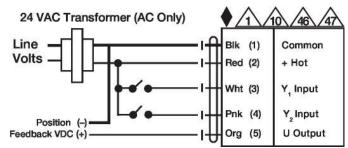


VDC/mA Control

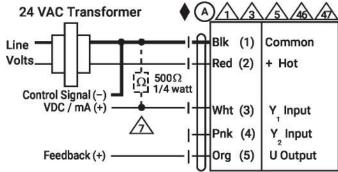


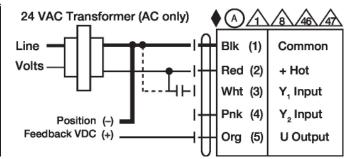




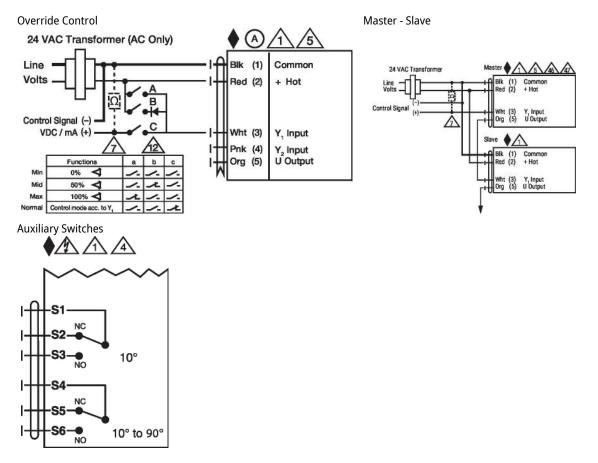


VDC/mA Control PWM Control









## **Dimensions**

